

The Geometry of Axisymmetric Ideal Fluid Flows with Swirl

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Abstract

The sectional curvature of the volume preserving diffeomorphism group of a Riemannian manifold M can give information about the stability of inviscid, incompressible fluid flows on M . We demonstrate that the submanifold of the volumorphism group of the solid flat torus generated by axisymmetric fluid flows with swirl, denoted by $\mathcal{D}_{\mu,E}(M)$, has positive sectional curvature in every section containing the field $X = u(r)\partial_\theta$ iff $\partial_r(ru^2) > 0$. This is in sharp contrast to the situation on $\mathcal{D}_\mu(M)$, where only Killing fields X have nonnegative sectional curvature in all sections containing it. We also show that this criterion guarantees the existence of conjugate points on $\mathcal{D}_{\mu,E}(M)$ along the geodesic defined by X .

Introduction

Let (M, g) be a Riemannian manifold of dimension at least two with Riemannian volume form μ . The configuration space for inviscid, incompressible fluid flows on M is the collection of volume-preserving diffeomorphisms (volumorphisms) of M , denoted by $\mathcal{D}_\mu(M)$. Arnold [1] demonstrated in 1966 that $\mathcal{D}_\mu(M)$ can be thought of as an infinite dimensional Riemannian manifold. He also showed that flows obeying the Euler equations for inviscid, incompressible fluid flow can be realized as geodesics on $\mathcal{D}_\mu(M)$. This was proved rigorously in the context of Sobolev manifolds by Ebin and Marsden [3]. Using this framework, questions of fluid mechanics can be re-phrased in terms of the Riemannian geometry of $\mathcal{D}_\mu(M)$. A good account of this is given in [2] or more recently in [6]. Of particular interest is the sectional curvature of $\mathcal{D}_\mu(M)$. As in finite dimensional geometry, given two geodesics with varying initial velocities in a region of strictly positive (resp. negative) sectional curvature, the two geodesics will converge (resp. diverge) via the Rauch Comparison theorem. In terms of fluid mechanics, this corresponds to the Lagrangian stability (resp. instability) of the associated fluid flows.

Arnold showed that the sectional curvature $K(X, Y)$ of the plane in $T_{\text{id}}\mathcal{D}_\mu(M)$ spanned by X and Y is often negative but occasionally positive. Rouchon [11] sharpened this to show that if $M \subset \mathbb{R}^3$, then $K(X, Y) \geq 0$ for every $Y \in T_{\text{id}}\mathcal{D}_\mu(M)$ if and only if X is a Killing field (i.e., one for which the flow generates a family of isometries). This result was generalized by Misiołek [7] and the second author [8] for any manifold with $\dim M \geq 2$. This gives the impression that, in general, $\mathcal{D}_\mu(M)$ will mostly be negatively curved. The question of when one can expect a divergence free vector field to give nonpositive sectional curvature remains open. However, the second author [9] provided criteria for divergence free vector fields of the form $X = u(r)\partial_\theta$ on the area-preserving diffeomorphism groups of a rotationally-symmetric surface for which the sectional curvature $K(X, Y)$ is nonpositive for all Y .

Our goal in this paper is to extend the curvature computation to $\mathcal{D}_{\mu,E}(M)$, the group of volumorphisms commuting with the flow of a Killing field E . In particular, we consider the solid flat torus, $M = D^2 \times S^1$, where D^2 is the unit disk in \mathbb{R}^2 and S^1 is the unit circle, as a subset

of \mathbb{R}^3 with the planes $z = 0$ and $z = 2\pi$ identified, where $E = \partial_\theta$ is the field corresponding to rotation in the disc. One may imagine fluid flows on this manifold as axisymmetric ideal flows with swirl on the solid infinite cylinder which are 2π -periodic in the z -direction. We consider steady fluid velocity fields of the form $X = u(r)\partial_\theta$. The submanifold $\mathcal{D}_{\mu,E}(M)$ is a totally geodesic submanifold of $\mathcal{D}_\mu(M)$, corresponding to the fact that an ideal fluid which is initially independent of θ will always remain so. Hence we compute sectional curvatures $K(X, Y)$ where $Y \in T_{\text{id}}\mathcal{D}_{\mu,E}(M)$ is divergence-free *and* axisymmetric, i.e., $[E, Y] = 0$.

In [9] we effectively showed that when X was considered as an element of $\mathcal{D}_{\mu,F}(M)$ where $F = \frac{\partial}{\partial z}$ (corresponding to considering X as a two-dimensional flow rather than a three-dimensional flow), the sectional curvature satisfied $K(X, Y) \leq 0$ for every $Y \in T_{\text{id}}\mathcal{D}_{\mu,F}(M)$ regardless of $u(r)$. By contrast we show here that if u satisfies the condition

$$\frac{d}{dr}(ru(r)^2) > 0, \quad (1)$$

then $K(X, Y) > 0$ for every $Y \in T_{\text{id}}\mathcal{D}_{\mu,E}(M)$. We will also show that $\frac{d}{dr}(ru(r)^2) \geq 0$ implies that $K(X, Y) \geq 0$. This does not contradict the result of Rouchon, since the proof of that result relies on being able to construct a divergence-free velocity field with small support which points in a given direction and is orthogonal to another direction, and there are not enough divergence-free vector fields in the axisymmetric case to accomplish this here.

The fact that the curvature is strictly positive in every section containing X makes it natural to ask whether there are conjugate points along every such corresponding geodesic. Unfortunately the Rauch comparison theorem cannot be used here, since $\inf_{Y \in T_{\text{id}}\mathcal{D}_{\mu,E}(M)} K(X, Y) = 0$ even if (1) holds. Nonetheless we can show that as long as

$$ru(r)u'(r) + 2u(r)^2 > 0, \quad (2)$$

the geodesic formed by $X = u(r)\partial_\theta$ has infinitely many monoconjugate points. It is easy to see that condition (1) implies (2). We do this by solving the Jacobi equation explicitly. As in [4], where the case $u(r) = 1$ was considered, we can prove that these monoconjugate points have an epiconjugate point as a limit point, so that the differential of the exponential map is not Fredholm.

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The Formula for Curvature

We first compute the curvature of $\mathcal{D}_{\mu,E}(M)$ by expanding in a Fourier series in z . Notice first of all that any vector field Y which is tangent to $\mathcal{D}_{\mu,E}(M)$ at the identity must be divergence-free and must commute with $E = \frac{\partial}{\partial \theta}$. Therefore we can write in the form

$$Y(r, z) = -\frac{g_z(r, z)}{r} \partial_r + \frac{g_r(r, z)}{r} \partial_z + f(r, z) \partial_\theta, \quad (3)$$

where $f(0, z) = g(0, z) = 0$ and $g(1, z)$ is constant in z (in order to be well-defined on the axis of symmetry and to have Y tangent to the boundary $r = 1$). We think of the term $-\frac{g_z}{r} \partial_r + \frac{g_r}{r} \partial_z$ as an analogue of the skew-gradient in two dimensions. We may express Y in a Fourier series in z as $Y(r, z) = \sum_{n \in \mathbb{Z}} Y_n(r, z)$ where

$$Y_n(r, z) = e^{inz} \left[-\frac{in}{r} g_n(r) \partial_r + \frac{g'_n(r)}{r} \partial_z + f_n(r) \partial_\theta \right]. \quad (4)$$

On any Riemannian manifold (M, g) with volume form μ , a formula for the curvature tensor on $\mathcal{D}_\mu(M)$ is given by

$$R(Y, X)X = P(\nabla_Y P(\nabla_X X) - \nabla_X P(\nabla_Y X) + \nabla_{[X, Y]}X), \quad (5)$$

where $P(X)$ is the projection onto the divergence-free part of X . Concretely, $P(X)$ is obtained by solving the Neumann boundary value problem

$$\begin{cases} \Delta q = \operatorname{div} X & \text{in } M \\ \langle \nabla q, \vec{n} \rangle = \langle X, \vec{n} \rangle & \text{on } \partial M \end{cases}$$

for q and then setting $P(X) = X - \nabla q$. The non-normalized sectional curvature is then given by

$$\overline{K}(X, Y) = \langle R(Y, X)X, \overline{Y} \rangle = \int_M \langle R(Y, X)X, \overline{Y} \rangle \mu. \quad (6)$$

See [7] for the derivation of the formula we use here. We first compute $R(Y_n, X)X$.

Proposition 1. *Let $M = D^2 \times S^1$. Suppose that $X \in T_{id}\mathcal{D}_{\mu, E}(M)$ is defined by $X = u(r)\partial_\theta$, and let Y_n be of the form (4). Then the curvature tensor $R(Y_n, X)X$ is given by*

$$R(Y_n, X)X = P\left(-inug_n(2u' + \frac{u}{r})e^{inz}\partial_r + \frac{(q'_n + rf_nu)ue^{inz}}{r}\partial_\theta\right), \quad (7)$$

where q_n is the solution of the ODE

$$\begin{cases} \frac{1}{r} \frac{d}{dr} \left(r \frac{dq_n}{dr} \right) - n^2 q_n(r) = -\frac{1}{r} \frac{d}{dr} (r^2 f_n(r) u(r)) & \text{for } 0 < r < 1 \\ q'_n(1) = -f_n(1)u(1) \\ |q_n(0)| < \infty \end{cases} \quad (8)$$

Proof. We compute using formula (5). First note that $\nabla_X X = -ru^2\partial_r$, which is the gradient of a function. Thus $P(\nabla_X X) = 0$. Next for $n = 0$ note that

$$Y_0 = \frac{1}{r} g'_0(r)\partial_z + f_0(r)\partial_\theta$$

and $\nabla_{Y_0} X = -rf_0(r)u(r)\partial_r$.

This is also the gradient of a function, and thus

$$P(\nabla_{Y_0} X) = 0.$$

Now for $n \neq 0$,

$$\nabla_{Y_n} X = -rf_nue^{inz}\partial_r - \frac{in}{r}g_n(u' + \frac{u}{r})e^{inz}\partial_\theta.$$

The solution $q_n(r)e^{inz}$ of

$$\begin{cases} \Delta(q_n(r)e^{inz}) = \operatorname{div}(\nabla_{Y_n} X) & \text{in } M, \\ \langle \nabla(q_n e^{inz}), \vec{n} \rangle|_{\partial M} = \langle \nabla_{Y_n} X, \vec{n} \rangle|_{\partial M} & \text{on } \partial M, \end{cases} \quad (9)$$

clearly must satisfy (8). With this solution in hand we will get

$$\nabla_X(P(\nabla_{Y_n}X)) = inug_n \left(u' + \frac{u}{r} \right) e^{inz} \partial_r - \frac{(q'_n + rf_n u) u e^{inz}}{r} \partial_\theta.$$

We also easily compute

$$\nabla_{[X,Y]}X = -ing_n(r)u(r)u'(r)e^{inz} \partial_r.$$

So, R will be given by (7). □

To get a more explicit and useful formula for curvature, we proceed to solve the ODE (8).

Lemma 2. *If q_n satisfies (8), then the solution is given by*

$$q_n(r) = -\zeta_n(r)H_n(r) + \xi_n(r)J_n(r), \quad (10)$$

where

$$H_n(r) = \int_0^r s^2 f_n(s) u(s) \xi'_n(s) ds \quad \text{and} \quad J_n(s) = - \int_r^1 s^2 f_n(s) u(s) \zeta'_n(s) ds, \quad (11)$$

and

$$\xi_n(r) = I_0(nr) \quad \text{and} \quad \zeta_n(r) = \frac{K_1(n)}{I_1(n)} I_0(nr) + K_0(nr),$$

with I_0 and K_0 denoting the modified Bessel functions of the first and second kinds.

Proof. Since I_0 and K_0 solve the homogeneous version of (8), this is essentially just the variation of parameters formula together with an integration by parts. We simply verify the solution: taking the derivative of $q_n(r)$, we obtain

$$\begin{aligned} q'_n(r) &= -\zeta'_n(r)H_n(r) + \xi'_n(r)J_n(r) + r^2 f_n(r)u(r)(\xi_n(r)\zeta'_n(r) - \zeta_n(r)\xi'_n(r)) \\ &= -\zeta'_n(r)H_n(r) + \xi'_n(r)J_n(r) - r f_n(r)u(r), \end{aligned} \quad (12)$$

and since $\zeta'_n(1) = J_n(1) = 0$ we get the correct boundary condition. Furthermore we get

$$q''_n(r) = -\zeta''_n(r)H_n(r) + \xi''_n(r)J_n(r) - \frac{d}{dr}(r f_n(r)u(r)),$$

and with these formulas we easily check that q_n satisfies (8). □

Plugging in the formula for q_n from Lemma 2 to the formula from Proposition 1, we obtain a very simple result.

Theorem 3. *On $M = D^2 \times S^1$ with $X = u(r) \partial_\theta$ and Y expressed as in (3), the non-normalized sectional curvature is given by $\overline{K}(X, Y) = \sum_{n \in \mathbb{Z}} \overline{K}(X, Y_n)$, where Y_n is expressed as in (4) and*

$$\overline{K}(X, Y_n) = 4\pi^2 \int_0^1 \frac{1}{r} \left(n^2 |g_n(r)|^2 \frac{d}{dr}(ru(r)^2) + \frac{|H_n(r)|^2}{I_1(nr)^2} \right) dr. \quad (13)$$

Hence the curvature is positive for all Y if and only if $\frac{d}{dr}(ru(r)^2) > 0$.

Proof. Using formula (12) in (7), we obtain

$$R(Y_n, X)X = P \left[(-inug_n(2u' + \frac{u}{r})e^{inz})\partial_r + \frac{u(\xi'_n J_n - \zeta'_n H_n)e^{inz}}{r}\partial_\theta \right],$$

which can clearly be expressed as e^{inz} times a function of r only. Orthogonality of the functions e^{imz} and e^{inz} over S^1 when $m \neq n$ implies that

$$\overline{K}(X, Y) = \sum_{m, n \in \mathbb{Z}} \langle Y_m, R(Y_n, X)X \rangle = \sum_{n \in \mathbb{Z}} \langle \overline{Y}_n, R(Y_n, X)X \rangle = \sum_{n \in \mathbb{Z}} \overline{K}(X, Y_n).$$

The latter is now relatively easy to compute. We have

$$\overline{K}(X, Y_n) = 4\pi^2 \int_0^1 \frac{n^2}{r^2} |g_n(r)|^2 \eta(r) dr + 4\pi^2 \int_0^1 r^2 \overline{f'_n(r)} \left(u(r) (\xi'_n(r) J_n(r) - \zeta'_n(r) H_n(r)) \right) dr, \quad (14)$$

where $\eta(r) = \frac{d}{dr}(ru(r)^2)$. By the definitions (11) of H_n and J_n , we see that the second term in (14) is

$$4\pi^2 \int_0^1 (\overline{H'_n(r)} J_n(r) - \overline{J'_n(r)} H_n(r)) dr.$$

From here we adapt the corresponding computation in [10]. Integrating by parts and using the fact that $J_n(r)\overline{H'_n(r)} \rightarrow 0$ as $r \rightarrow 0$ or $r \rightarrow 1$, we get

$$\int_0^1 \overline{H'_n(r)} J_n(r) - \overline{J'_n(r)} H_n(r) dr = -2\text{Re} \int_0^1 \overline{J'_n(r)} H_n(r) dr = \int_0^1 \frac{J'_n(r)}{H'_n(r)} \frac{d}{dr} (|H_n(r)|^2) dr,$$

and another integration by parts (where again the boundary terms vanish) gives

$$\int_0^1 \overline{H'_n(r)} J_n(r) - \overline{J'_n(r)} H_n(r) dr = - \int_0^1 \frac{d}{dr} \left(\frac{K_1(nr)}{I_1(nr)} \right) |H_n(r)|^2 dr.$$

Finally the Bessel function identity $\frac{d}{dr} \left(\frac{K_1(r)}{I_1(r)} \right) = \frac{1}{rI_1(r)^2}$ implies (13). \square

Remark 4. The normalized sectional curvature is given by $K(X, Y) = \frac{\overline{K}}{\langle X, X \rangle \langle Y, Y \rangle - \langle X, Y \rangle^2}$. Suppose that $f = 0$ and that only one g_n is nonzero in (4); then we have $\langle X, Y \rangle = 0$ and the sectional curvature takes the form

$$K(X, Y) = \frac{n^2 \int_0^1 \frac{1}{r} |g_n(r)|^2 \frac{d}{dr}(ru(r)^2) dr}{\left(\int_0^1 r^3 u(r)^2 dr \right) \left(\int_0^1 \left(\frac{n^2}{r} |g_n(r)|^2 + |g'_n(r)|^2 \right) dr \right)}.$$

We can make this arbitrarily small by choosing a highly oscillatory g_n . Hence although the curvature is strictly positive if $\frac{d}{dr}(ru(r)^2) > 0$, it cannot be bounded below by any positive constant.

Solution of the Jacobi equation

It is natural to ask whether the positive curvature guaranteed by the theorem above ensures the existence of conjugate points along the corresponding geodesic. This is not automatic since although the sectional curvature is positive in all sections containing the geodesic's tangent vector, it is not bounded below by any positive constant because of Remark 4; hence the Rauch comparison theorem cannot be applied directly. In this section we answer this question affirmatively by solving the Jacobi equation more or less explicitly along such a geodesic, and show that in fact conjugate points occur rather frequently.

Theorem 5. Let $\eta(t)$ be a geodesic on $\mathcal{D}_{\mu,E}(D^2 \times S^1)$ with initial condition $\eta(0) = id$ and $\dot{\eta}(0) = X = u(r)\partial_\theta$. Let $\omega(r) = 2u(r) + ru'(r)$ denote the vorticity function of X , and assume that $u(r)\omega(r) > 0$ for all $r \in [0, 1]$. Then $\eta(t)$ is a monoconjugate point to $\eta(0)$ for every time $t = 2\pi\lambda/n$, where $n \in \mathbb{N}$ is arbitrary and λ is any eigenvalue of the Bessel-type Sturm-Liouville problem

$$\frac{1}{r} \frac{d}{dr}(r\psi'(r)) - \left(n^2 + \frac{1}{r^2}\right)\psi(r) = -2\lambda^2 u(r)\omega(r)\psi(r), \quad \psi(1) = 0, \quad \psi(0) \text{ finite.}$$

Proof. Along a geodesic $\eta(t)$ with (steady) Eulerian velocity field X , the Jacobi equation for a Jacobi field $J(t) = Y(t) \circ \eta(t)$ may be written [8] as the system

$$\frac{\partial Y}{\partial t} + [X, Y(t)] = Z(t) \tag{15}$$

$$\frac{\partial Z}{\partial t} + P(\nabla_X Z(t) + \nabla_{Z(t)} X) = 0, \tag{16}$$

where P is the orthogonal projection onto divergence-free vector fields. The first equation is the linearized flow equation, while the second is the linearized Euler equation used in stability analysis. Write

$$Z(t, r, z) = -\frac{1}{r} \frac{\partial h}{\partial z}(t, r, z) \partial_r + \frac{1}{r} \frac{\partial h}{\partial r}(t, r, z) \partial_z + j(t, r, z) \partial_\theta,$$

where $h = 0$ on the axis $r = 0$ and h is constant on the boundary $r = 1$. Then it is easy to compute that (16) becomes the system

$$\frac{\partial j}{\partial t}(t, r, z) = \frac{\omega(r)}{r^2} \frac{\partial h}{\partial z}(t, r, z), \tag{17}$$

$$-\frac{1}{r} \frac{\partial^2 h}{\partial t \partial z}(t, r, z) \partial_r + \frac{1}{r} \frac{\partial^2 h}{\partial t \partial r}(t, r, z) \partial_z = 2P(ru(r)j(t, r, z) \partial_r), \tag{18}$$

where $\omega(r) = 2u(r) + ru'(r)$ is the vorticity defined by $\text{curl } X = \omega(r) \partial_z$. Applying the curl to both sides of equation (18) to eliminate the projection operator, we obtain

$$\frac{\partial}{\partial t} \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial h}{\partial r} \right) + \frac{1}{r} \frac{\partial^2 h}{\partial z^2} \right] = -2ru(r) \frac{\partial j}{\partial z}. \tag{19}$$

Differentiating (19) in time and substituting (17) we obtain the single equation

$$\frac{\partial^2}{\partial t^2} \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial h}{\partial r} \right) + \frac{1}{r} \frac{\partial^2 h}{\partial z^2} \right] = -\frac{2u(r)\omega(r)}{r} \frac{\partial^2 h}{\partial z^2}. \tag{20}$$

Expand h in a Fourier series in z to get

$$h(t, r, z) = \sum_{n \in \mathbb{Z}} h_n(t, r) e^{inz}.$$

Then for each n we can solve the eigenvalue problem

$$\frac{d}{dr} \left(\frac{1}{r} \phi'(r) \right) - \frac{n^2}{r} \phi(r) = \frac{2Cu(r)\omega(r)}{r} \phi(r);$$

to make this look more familiar we set $\phi(r) = r\psi(r)$ and obtain

$$\frac{1}{r} \frac{d}{dr}(r\psi'(r)) - \left(n^2 + \frac{1}{r^2}\right)\psi(r) = 2Cu(r)\omega(r)\psi(r),$$

which is a singular Sturm-Liouville problem analogous to the Bessel equation. We obtain a sequence of eigenfunctions $\phi_{mn}(r)$ for $m \in \mathbb{N}$, with eigenvalues C_{mn} . We see that

$$2C \int_0^1 \frac{u(r)\omega(r)}{r} \phi(r)^2 dr = - \int_0^1 \frac{1}{r} \phi'(r)^2 dr - \int_0^1 \frac{n^2}{r} \phi(r)^2 dr,$$

so that if $\omega(r)u(r) > 0$, then C must be strictly negative; we write $C = -\lambda_{mn}^2$ for the eigenfunction $\phi_{mn}(r)$. Expanding $h_n(t, r)$ in a basis of such eigenfunctions as

$$h(t, r, z) = \sum_{n \in \mathbb{Z}} \sum_{m=1}^{\infty} h_{mn}(t) \phi_{mn}(r) e^{inz},$$

equation (20) becomes

$$-\lambda_{mn}^2 h_{mn}''(t) = n^2 h_{mn}(t),$$

which obviously has solutions

$$h_{mn}(t) = a_{mn} \cos\left(\frac{nt}{\lambda_{mn}}\right) + b_{mn} \sin\left(\frac{nt}{\lambda_{mn}}\right)$$

for some coefficients a_{mn} and b_{mn} .

Suppose $a_{m,n} = a_{m,-n} = \frac{1}{2}$ for some (m, n) with $n \neq 0$, and that all other a are zero and that every b is zero, so that $h(t, r, z) = \cos\left(\frac{nt}{\lambda_{mn}}\right) \phi_{mn}(r) \cos nz$. Then by equation (19) we compute that

$$j(t, r, z) = -\frac{\lambda_{mn}\omega(r)}{r^2} \phi_{mn}(r) \sin nz \sin\left(\frac{nt}{\lambda_{mn}}\right).$$

To find the Jacobi fields, write Y in equation (15) as

$$Y(t, r, z) = -\frac{1}{r} \frac{\partial g}{\partial z}(t, r, z) \partial_r + \frac{1}{r} \frac{\partial g}{\partial r}(t, r, z) \partial_z + f(t, r, z) \partial_\theta.$$

We easily compute that $X = u(r) \frac{\partial}{\partial \theta}$ gives $[X, Y] = \frac{1}{r} \frac{\partial g}{\partial z} u'(r) \frac{\partial}{\partial \theta}$, and thus equation (15) becomes in components

$$\begin{aligned} \frac{\partial g}{\partial t}(t, r, z) &= h(t, r, z) \\ \frac{\partial f}{\partial t}(t, r, z) + \frac{u'(r)}{r} \frac{\partial g}{\partial z}(t, r, z) &= j(t, r, z). \end{aligned}$$

With $g(0, r, z) = f(0, r, z) = 0$, we find that

$$\begin{aligned} g(t, r, z) &= \frac{\lambda_{mn}}{n} \cos nz \sin\left(\frac{nt}{\lambda_{mn}}\right) \phi_{mn}(r) \\ f(t, r, z) &= \frac{2\lambda_{mn}^2 u(r)}{nr^2} \sin nz \left(\cos\left(\frac{nt}{\lambda_{mn}}\right) - 1 \right) \phi_{mn}(r). \end{aligned}$$

Thus both f and g vanish when $t = 0$ and when $t = 2\pi\lambda_{mn}/n$, so $\eta(2\pi\lambda_{mn}/n)$ is monoconjugate to the identity along η . \square

Remark 6. *Using the Sturm comparison theorem we can estimate the spacing of the eigenvalues λ_{mn} and show that for fixed m the sequence λ_{mn}/n has a finite limit as $n \rightarrow \infty$. Just as in [4], this must be an epiconjugate point. Therefore the differential of the exponential map is not Fredholm along any geodesic of this form. It is worth noting that the reason the Jacobi equation is explicitly solvable in this case is because there is no “drift” term, so the total time derivative agrees with the partial time derivative, in the same way as in [4].*

It would be very interesting to generalize the curvature computation to fields of the form $X = u(r) \sin z \partial_\theta$, which is the initial velocity field of the Hou-Luo initial condition [5] that leads numerically to a blowup solution. We expect that the formula $\int \overline{H'_n} J_n - \overline{J'_n} H_n$ which appears both here and in [9] is a typical feature of curvature formulas when computed correctly, although they doubtless become substantially more complicated.

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